

Designing New Phase selection Heuristics

Arijit Shaw • Kuldeep S. Meel



Conflict Driven Clause Learning (CDCL)

CDCL(F)

```
A ← {}
while hasUnassignedVars( $F$ )
    A ← A ∪ { DECIDE( $F, A$ ) }
    while BCP( $F, A$ ) = conflict
        ( $b, c \boxtimes$  ← ANALYZECONFLICT())
        if  $b < 0$  then return unsat
        else BACKTRACK( $F, A, b$ )
        if clauseDeletionRequired()
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    return sat
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Decision Heuristics

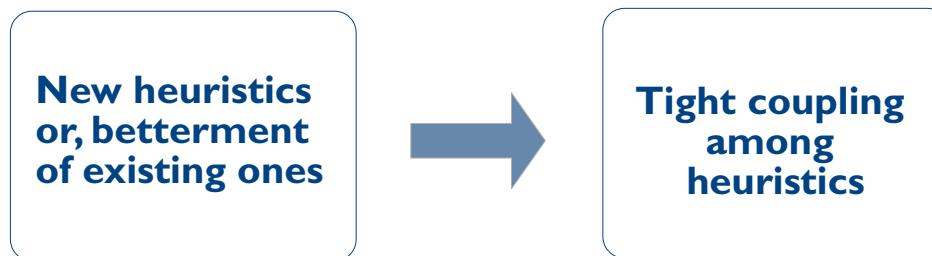
Clause Maintenance
Heuristics

Restart Heuristics

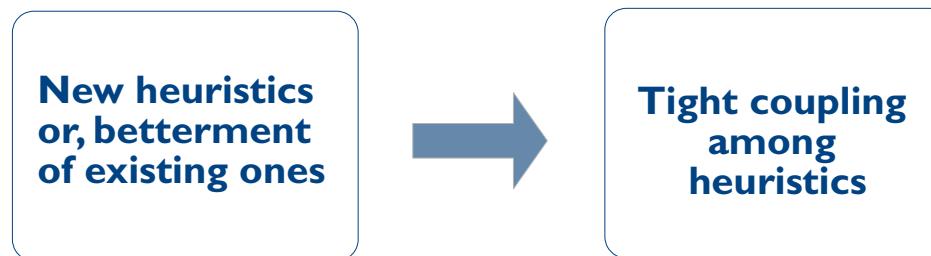
Development of Solvers

New heuristics
or, betterment
of existing ones

Development of Solvers



Development of Solvers

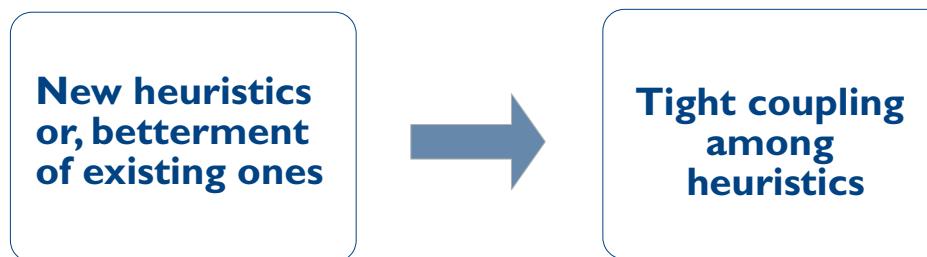


unclear whether
VMTF only works in
combination with
Glucose restarts

Evaluating CDCL Variable
Scoring Schemes (SAT'15)

Armin Biere and Andreas Fröhlich

Development of Solvers



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**Between SAT and UNSAT:
The Fundamental Difference
in CDCL SAT (SAT'15)**

Chanseok Oh

**Evaluating CDCL Variable
Scoring Schemes (SAT'15)**

Armin Biere and Andreas Fröhlich



we decided to use the
(VSIDS decay) factor of
0.999 in the no restart
phase. For the Glucose
(restart) phase, however,
we retained the default
value of 0.95

Heuristics under study

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phase selection heuristic

backtracking strategy

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Phase Saving

backtracking strategy

Chronological Backtracking

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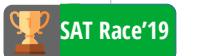
Chronological Backtracking

Who uses?



SATComp'18

- 1) Maple_LCM_Dist_ChronoBT
- 2) Maple_LCM_Dist_ChronoBTv3
- 3) CryptoMiniSat



SAT Race'19

Heuristics under study

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SAT Race'19

Phase-Saving

a phase selection heuristic

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**A Lightweight
Component Caching Scheme
For Satisfiability Solvers
(SAT'07)**

Knot Pipatsrisawat and Adnan Darwiche

Phase-Saving

a phase selection heuristic

A Lightweight
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Data
Strucure

Update
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on SAT '19 instances

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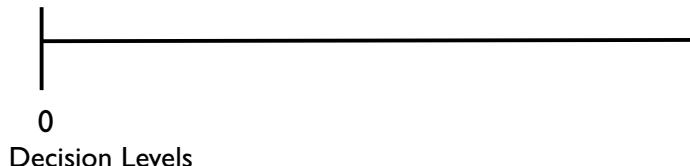
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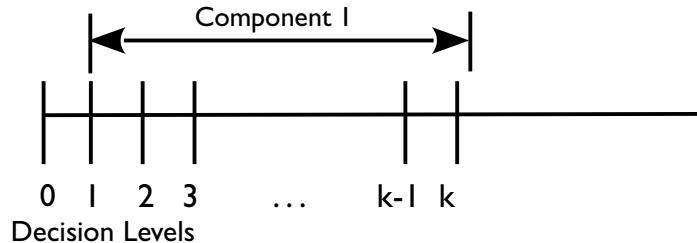
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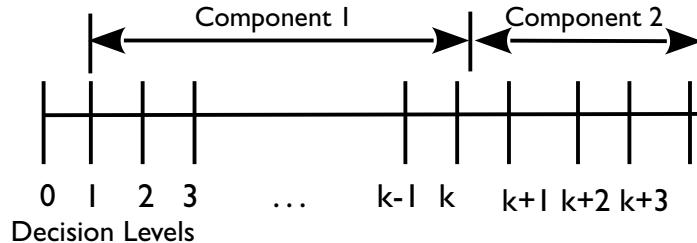
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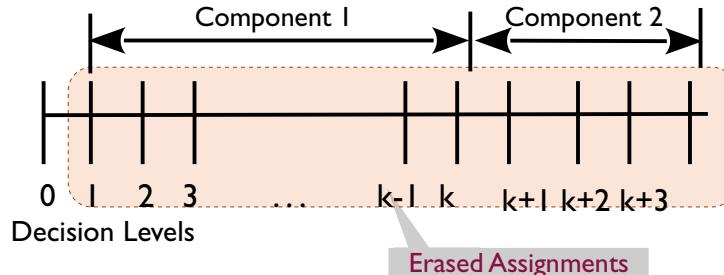
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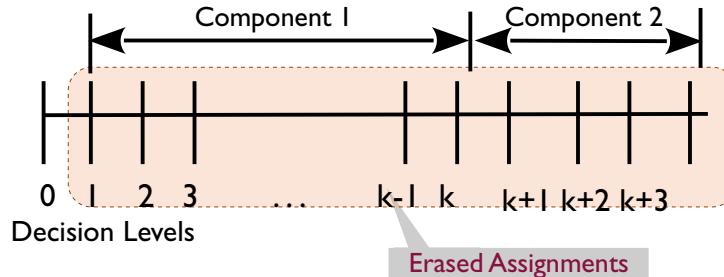
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Key Idea! : Do not lose work in long backtracks

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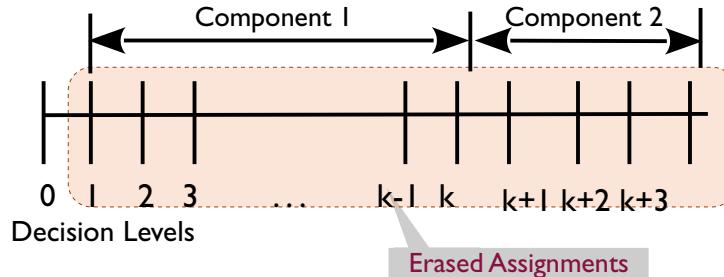
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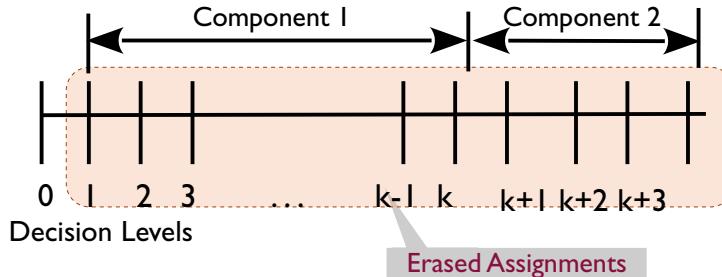
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Chronological Backtracking

When CDCL is all about Non- Chronological Backtracking

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**Chronological
Backtracking (SAT'18)**

Alexander Nadel and Vadim Ryvchin

Chronological Backtracking

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Notation

$\neg X_7 @ 1$ decision

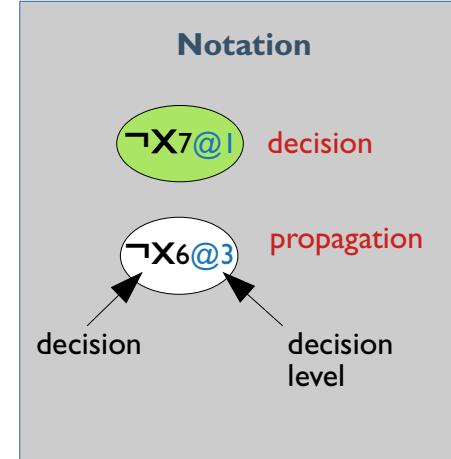
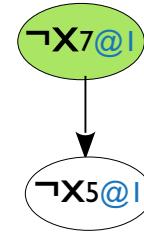
$\neg X_6 @ 3$ propagation

decision

decision level

Chronological Backtracking

When CDCL is all about Non- Chronological Backtracking



Chronological
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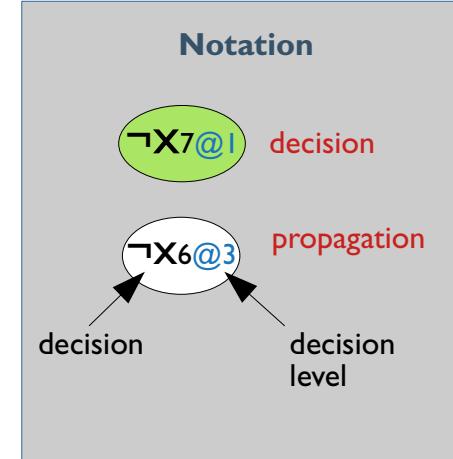
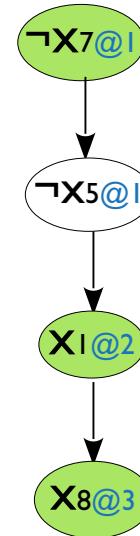
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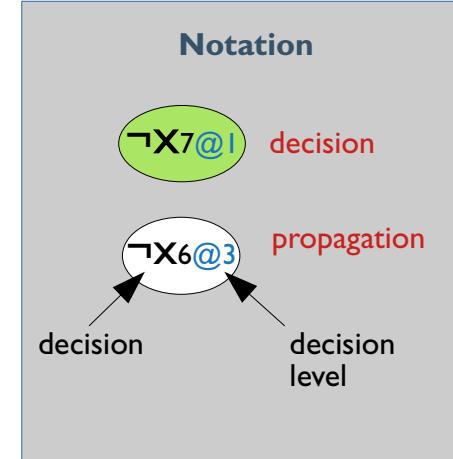
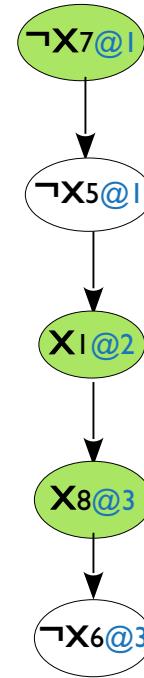


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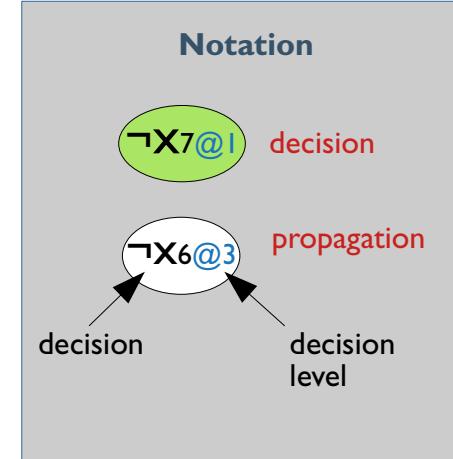
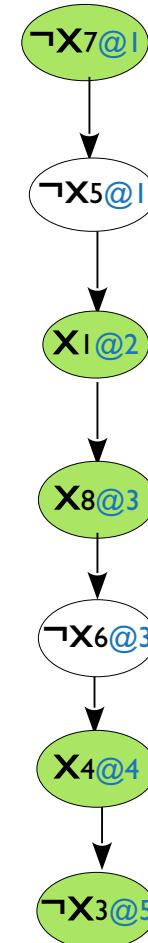


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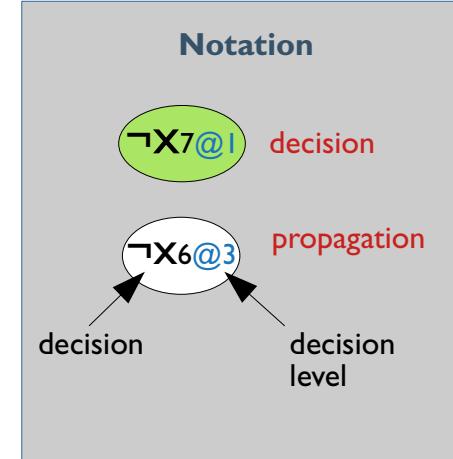
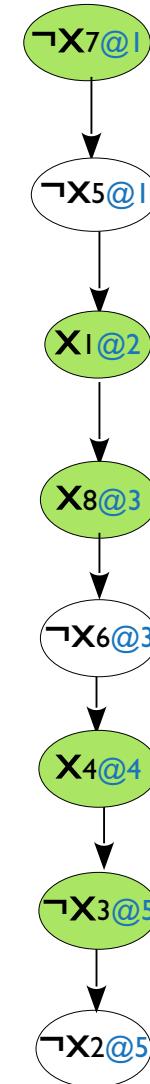


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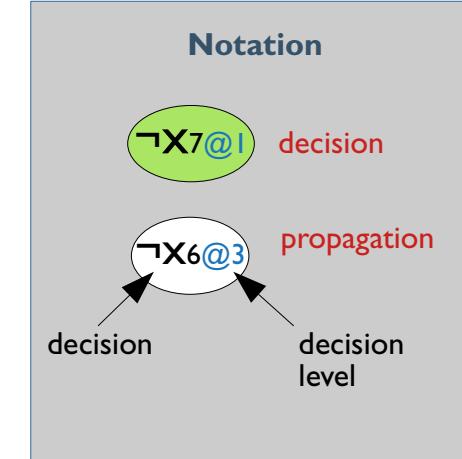
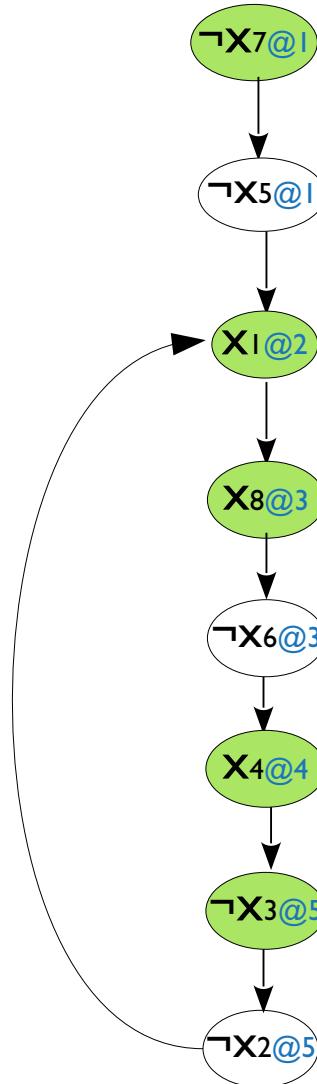


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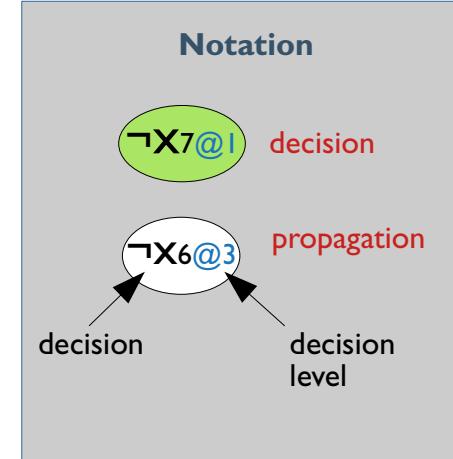
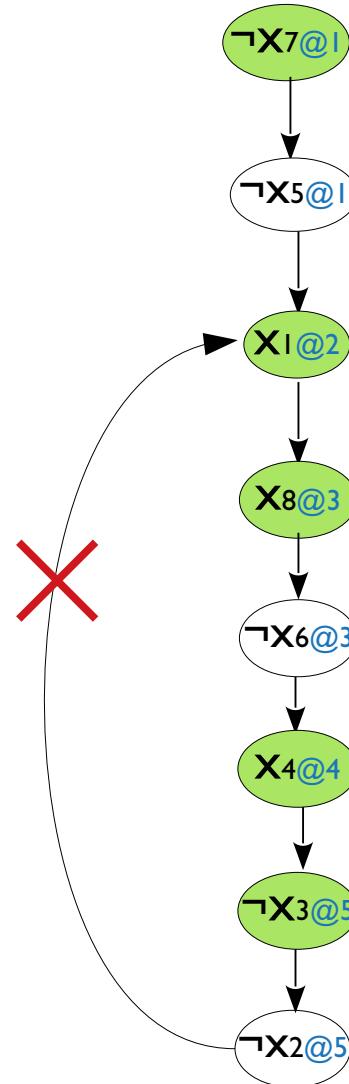


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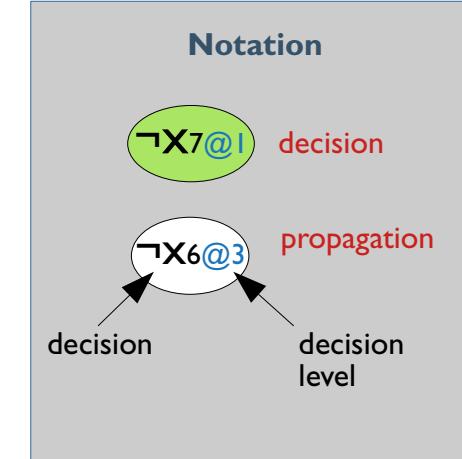
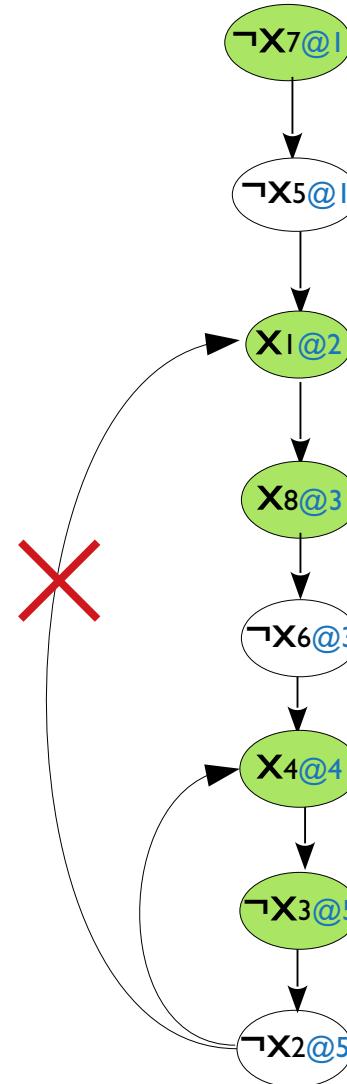


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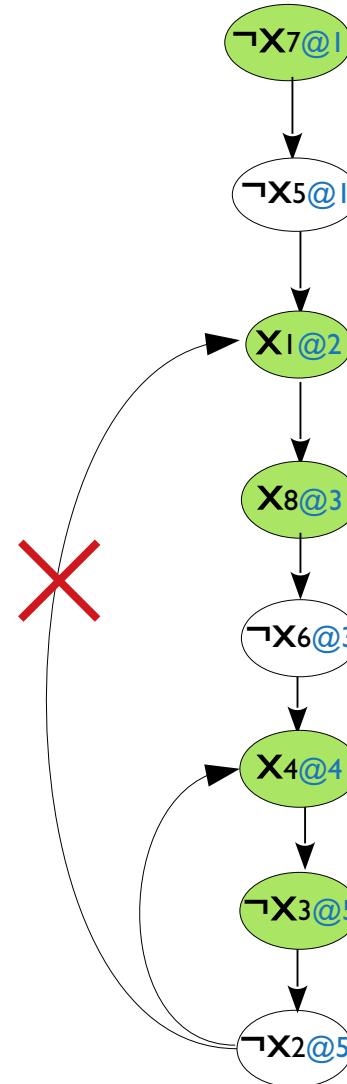
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**Backing Backtracking
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Sibylle Möhle and Armin Biere



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$\neg X_6 @ 3$ propagation

decision

decision level

Chronological Backtracking

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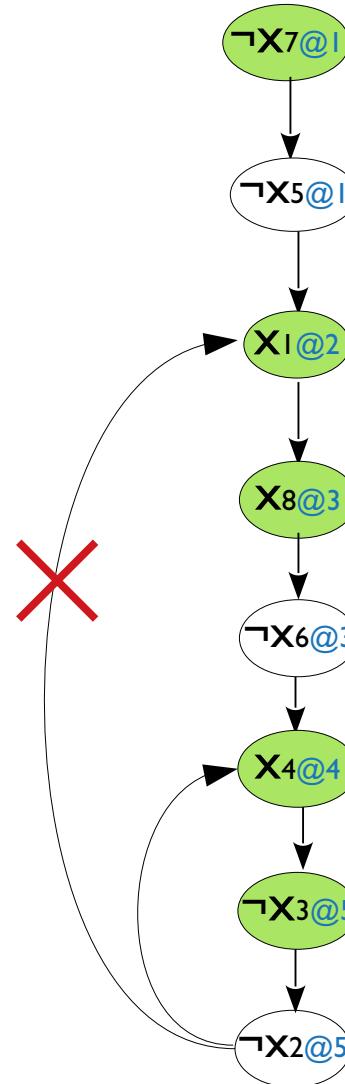
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Notation



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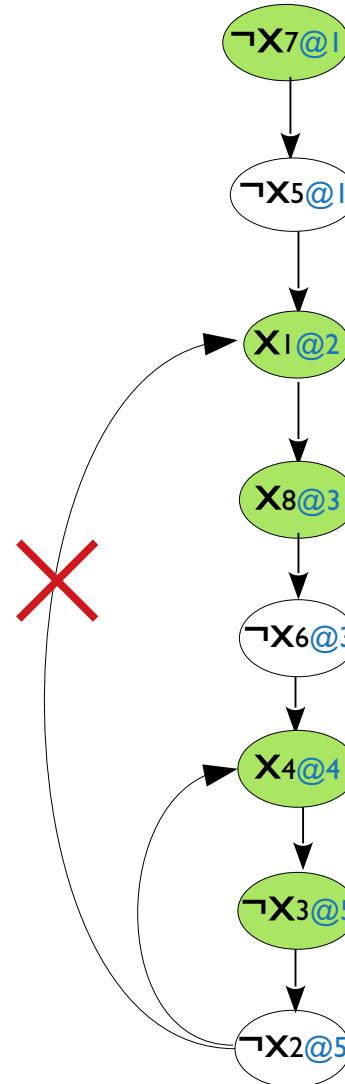
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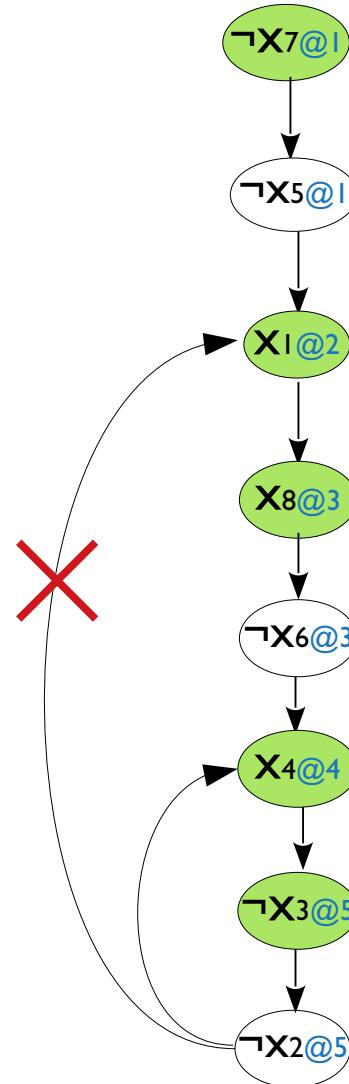
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Question : Is phase saving still useful,
if the solver backtracks chronologically?



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How well are they together?

Testing coupling of Phase Saving and Chronological Backtracking
(CB)

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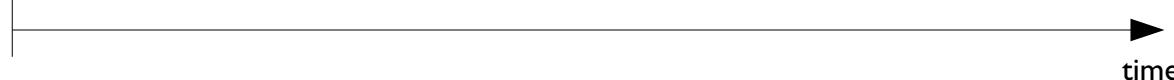
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Introduce
CB-state
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NCB-state

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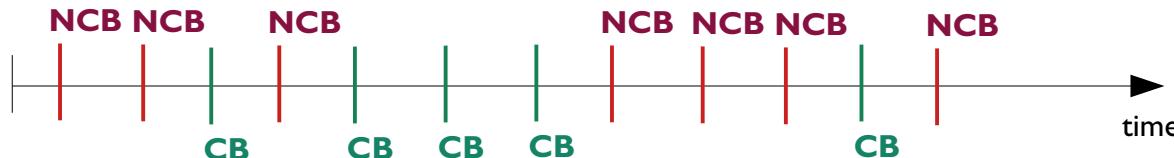
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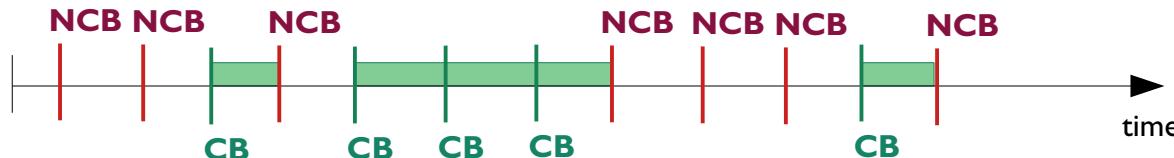
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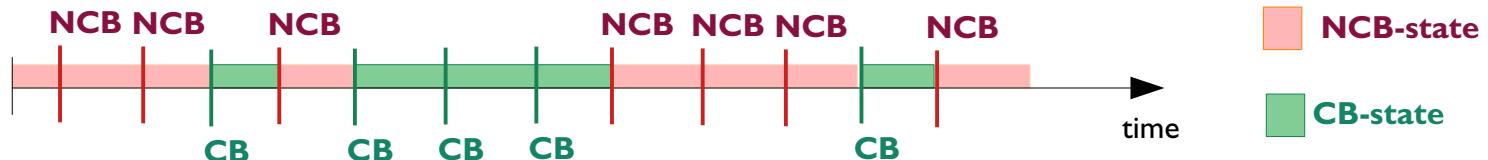
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Testing coupling of Phase Saving and Chronological Backtracking
(CB)

Introduce
CB-state
and
NCB-state



Vary
phase selection
heuristics
in CB-state



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Phase Selection Heuristic used		Instances solved	Avg. Runtime*
NCB-state	CB-state		
Phase Saving	Phase Saving		
Phase Saving	Random		

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Phase Selection Heuristic used		Instances solved	Avg. Runtime*
NCB-state	CB-state		
Phase Saving	Phase Saving	237	4607
Phase Saving	Random	239	4537

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NCB-state
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Phase Selection Heuristic used			
NCB-state	CB-state	Instances solved	Avg. Runtime*
Phase Saving	Phase Saving	237	4607
Phase Saving	Random	239	4537
Phase Saving	Always False	235	4679
Phase Saving	Opp. Phase Saving	237	4785

* Base Solver : Maple_LCM_Dist_ChronoBT_v3
Benchmarks : SAT Race '19



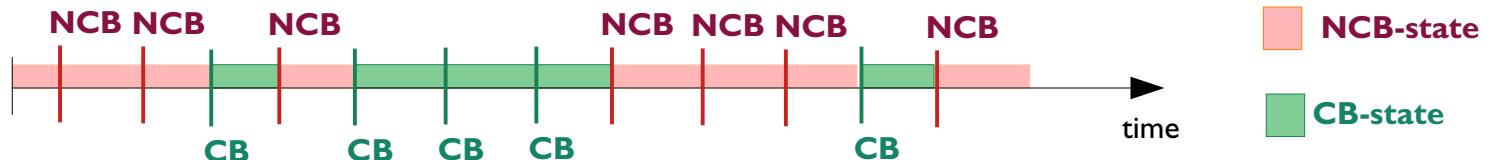
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Conclusion : Phase Saving's usefulness is not valid for CB.

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Decaying Phase Score (DPS)

Idea! : Capture the “**trend**” of phase for the variables

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Phase Saving				
x1	x2	x3	x4	x5
⊥	⊥	T	⊥	T

SavedPhase(v) = assignment(v)

return SavedPhase(v)



Decaying Phase Score (DPS)

Idea! : Capture the “trend” of phase for the variables

Phase Saving					DPS				
x1	x2	x3	x4	x5	x1	x2	x3	x4	x5
⊥	⊥	T	⊥	T	2.50	- 0.5	- 9.3	7.9	0.25
Data Strucure					Update during backtrack				
Phase Selection					SavedPhase(v) = assignment(v)				
return SavedPhase(v)									

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x1	x2	x3	x4	x5
2.50	- 0.5	- 9.3	7.9	0.25

Data
Strucure

Update
during
backtrack

Phase
Selection

$$\mathbf{DPS}(v) = \lambda \cdot \mathbf{DPS}(v) + \mathbf{polarity}(v)$$

$$0.5 < \lambda < 1.0$$

$$\begin{aligned} \mathbf{polarity}(T) &= +1 \\ \mathbf{polarity}(\perp) &= -1 \end{aligned}$$

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Data Structure

Update during backtrack

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**if DPS(v) > 0
then return true
else return false**

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solver	# solved	Avg. Runtime*
MLDC	237	4556
MLDC_DPS	239	4585

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SAT Race'19

LSIDS : Literal State Independent Decaying Sum

Key Idea! : Prioritize the phase which occur **more** and **recently** in learnt clauses.

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Decay

- Multiply each score by $f = 0.8$ at each conflict.

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Maintain the essence of **phase saving**

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Prioritize the phase which occur **recently**

LSIDS : a scoring scheme for literals

Literal State Independent Decaying Sum

Example!

Learnt Clauses :

c1 : $\neg x_1 \vee x_2 \vee \neg x_4$

c2 : $\neg x_1 \vee \neg x_2 \vee x_3$

c3 : $x_3 \vee \neg x_4$

x_1	$\neg x_1$	x_2	$\neg x_2$	x_3	$\neg x_3$	x_4	$\neg x_4$
0	0	0	0	0	0	0	0

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Bump

x_1	$\neg x_1$	x_2	$\neg x_2$	x_3	$\neg x_3$	x_4	$\neg x_4$
0	0	0	0	0	0	0	0
0	1	1	0	0	0	0	1

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Bump

x_1	$\neg x_1$	x_2	$\neg x_2$	x_3	$\neg x_3$	x_4	$\neg x_4$
0	0	0	0	0	0	0	0
0	I	I	0	0	0	0	I

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Bump
Decay

x_1	$\neg x_1$	x_2	$\neg x_2$	x_3	$\neg x_3$	x_4	$\neg x_4$
0	0	0	0	0	0	0	0
0	1	1	0	0	0	0	1
0	0.8	0.8	0	0	0	0	0.8

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Decay

Bump

x_1	$\neg x_1$	x_2	$\neg x_2$	x_3	$\neg x_3$	x_4	$\neg x_4$
0	0	0	0	0	0	0	0
0	1	1	0	0	0	0	1
0	0.8	0.8	0	0	0	0	0.8
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Decay

x_1	$\neg x_1$	x_2	$\neg x_2$	x_3	$\neg x_3$	x_4	$\neg x_4$
0	0	0	0	0	0	0	0
0	1	1	0	0	0	0	1
0	0.8	0.8	0	0	0	0	0.8
0	1.8	0.8	1	1	0	0	0.8
0	1.44	0.64	0.8	0.8	0	0	0.64

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x_1	$\neg x_1$	x_2	$\neg x_2$	x_3	$\neg x_3$	x_4	$\neg x_4$
0	0	0	0	0	0	0	0
0	1	1	0	0	0	0	1
0	0.8	0.8	0	0	0	0	0.8
0	1.8	0.8	1	1	0	0	0.8
0	1.44	0.64	0.8	0.8	0	0	0.64
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Decay

Bump

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Bump

x_1	$\neg x_1$	x_2	$\neg x_2$	x_3	$\neg x_3$	x_4	$\neg x_4$
0	0	0	0	0	0	0	0
0	1	1	0	0	0	0	1
0	0.8	0.8	0	0	0	0	0.8
0	1.8	0.8	1	1	0	0	0.8
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$\neg x_2$

Bump

Decay

Bump

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Bump

x_1	$\neg x_1$	x_2	$\neg x_2$	x_3	$\neg x_3$	x_4	$\neg x_4$
0	0	0	0	0	0	0	0
0	1	1	0	0	0	0	1
0	0.8	0.8	0	0	0	0	0.8
0	1.8	0.8	1	1	0	0	0.8
0	1.44	0.64	0.8	0.8	0	0	0.64
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Bump

Decay

Bump

Decay

Bump

Bump

x_1	$\neg x_1$	x_2	$\neg x_2$	x_3	$\neg x_3$	x_4	$\neg x_4$
0	0	0	0	0	0	0	0
0	1	1	0	0	0	0	1
0	0.8	0.8	0	0	0	0	0.8
0	1.8	0.8	1	1	0	0	0.8
0	1.44	0.64	0.8	0.8	0	0	0.64
0	1.44	0.64	0.8	1.8	0	0	1.64
0	1.44	0.64	2.8	1.8	0	0	1.64

LSIDS : a scoring scheme for literals

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Backtrack :

$\neg x_2$

Phase Selection

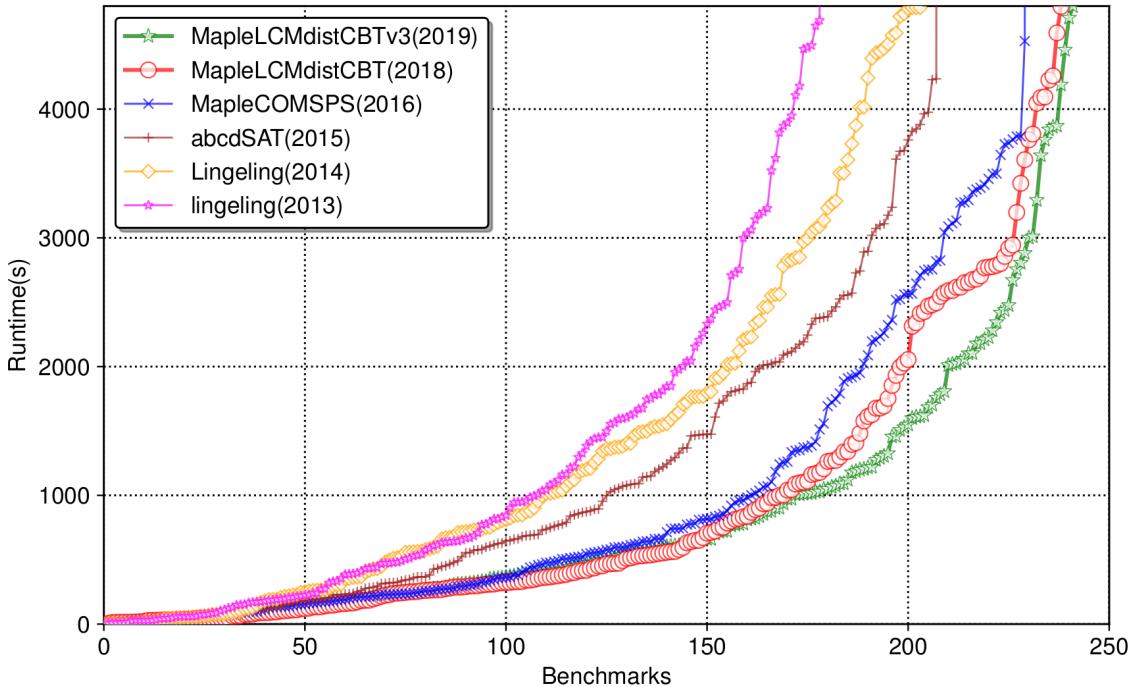
- Compare score of two literals of the variable.
- Choose the one with higher score.

x1	$\neg x_1$	x2	$\neg x_2$	x3	$\neg x_3$	x4	$\neg x_4$
0	0	0	0	0	0	0	0
Bump							
Decay							
0	1	1	0	0	0	0	1
Bump							
Decay							
0	0.8	0.8	0	0	0	0	0.8
Bump							
Decay							
0	1.8	0.8	1	1	0	0	0.8
Bump							
Decay							
0	1.44	0.64	0.8	0.8	0	0	0.64
Bump							
Decay							
0	1.44	0.64	0.8	1.8	0	0	1.64
Bump							
Decay							
0	1.44	0.64	2.8	1.8	0	0	1.64

SAT Revolution

over years 2013 - 19

SAT Revolution over years 2013 - 19



on SAT '19 benchmarks
5000s timeout

solver	year	# solved
lingeling	2013	179
lingeling	2014	188
abcdSAT	2015	202
MapleCOMSPS	2016	224
MapleLCMDistCBT	2018	233
MapleLCMDistCBTv3	2019	237

Results

on 400 SAT '19 instances

solver	# solved	Avg. Runtime*
MLDC		
MLDC_LSIDS		

* **MLDC** : Maple_LCM_Dist_ChronoBT_v3

* Avg. Runtime : PAR-2 scores



SAT Race'19

Results

on 400 SAT '19 instances

solver	# solved	Avg. Runtime*
MLDC	237	4556
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Room for being skeptical

- Is LSIDS complete noise?

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T : CB if (decision level - backtracking level) > T
C : NCB for first C conflicts

		T = 100				C = 4000			
		C = 2000	C = 3000	C = 4000	C = 5000	T = 25	T = 90	T = 150	T = 200
# solved	MLDC	235	237	235	234	237	233	229	235
	MLDC -LSIDS	242	240	243	239	241	238	238	239
Avg. Runtime	MLDC	4663	4588	4556	4674	4609	4706	4773	4641
	MLDC -LSIDS	4506	4558	4398	4575	4555	4556	4622	4583

Key Contribution

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 - “Issues serious warrant to the community.”

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Thanks !

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for useful observations.

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github.com/meelgroup/duriansat

Thanks !

Special Thanks to Mate Soos and Norbert Mantheny
for useful observations.

Key Contribution

- Discovery : Phase Saving is **not efficient** with CB.
 - “Issues serious warrant to the community.”
- Designing a phase selection which is **efficient** with CB.



github.com/meelgroup/duriansat

Thanks !

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